

Automatic Control (1)



By



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Lecture (3) – Part (1)





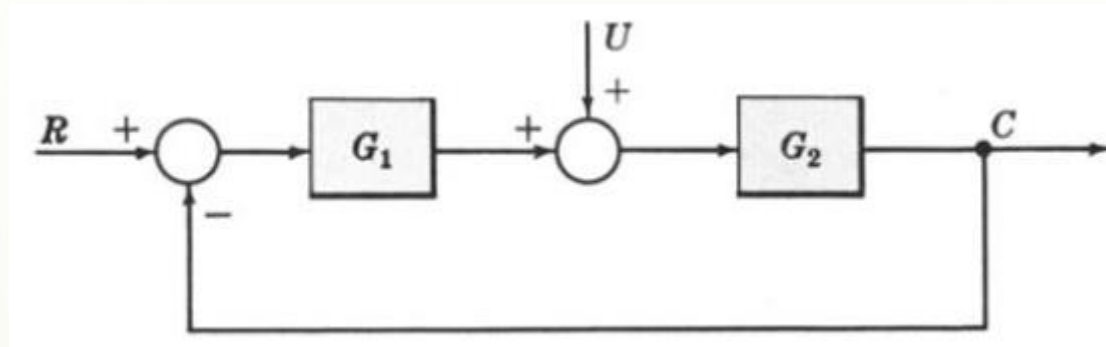
Block Diagram Fundamentals
&
Reduction Techniques
&
Signal-flow Graphs
&
State-Space Representation



Superposition of Multiple Inputs

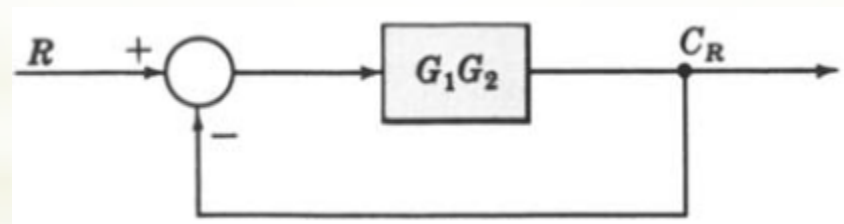
- Step 1:** Set all inputs except one equal to zero.
- Step 2:** Transform the block diagram to canonical form, using the transformations of Section 7.5.
- Step 3:** Calculate the response due to the chosen input acting alone.
- Step 4:** Repeat Steps 1 to 3 for each of the remaining inputs.
- Step 5:** Algebraically add all of the responses (outputs) determined in Steps 1 to 4. This sum is the total output of the system with all inputs acting simultaneously.

Example-15: **Multiple Input System.** Determine the output C due to inputs R and U using the Superposition Method.



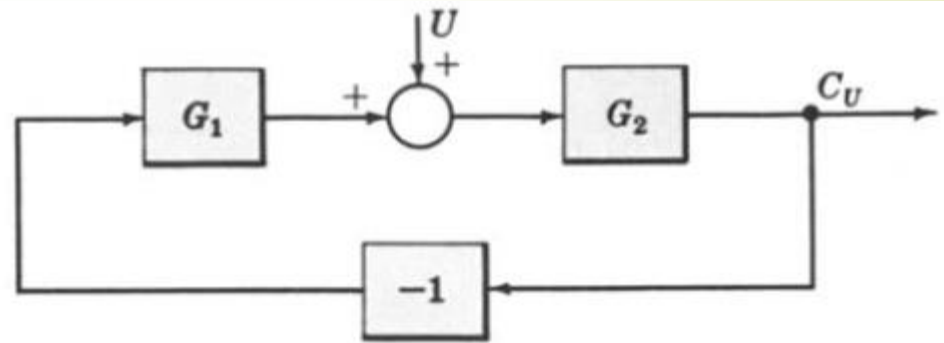
Step 1: Put $U \equiv 0$.

Step 2: The system reduces to



Step 3:

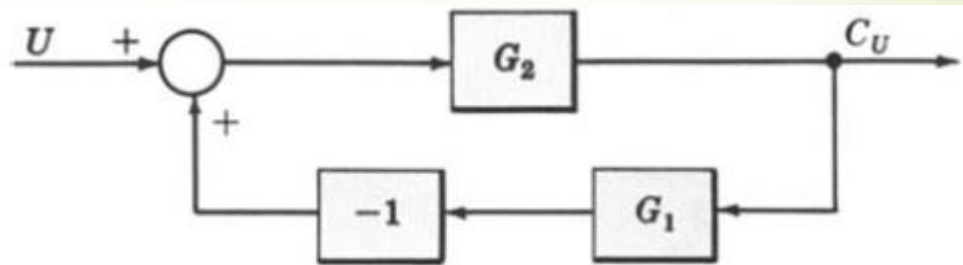
the output C_R due to input R is $C_R = [G_1G_2/(1 + G_1G_2)]R$



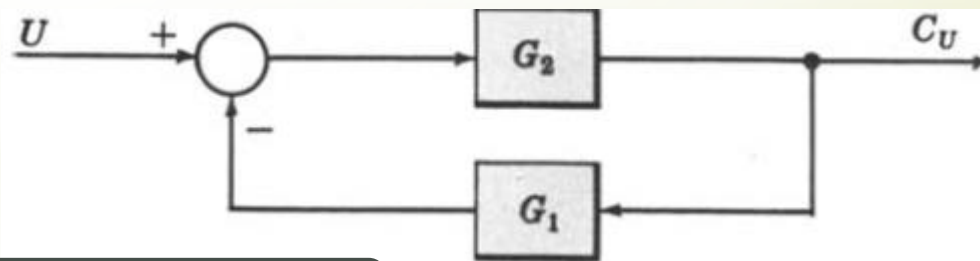
Step 4a: Put $R = 0$.

Step 4b: Put -1 into a block, representing the negative feedback effect:

Rearrange the block diagram:



Let the -1 block be absorbed into the summing point:



Step 4c: the output C_U due to input U is $C_U = [G_2 / (1 + G_1 G_2)] U$.

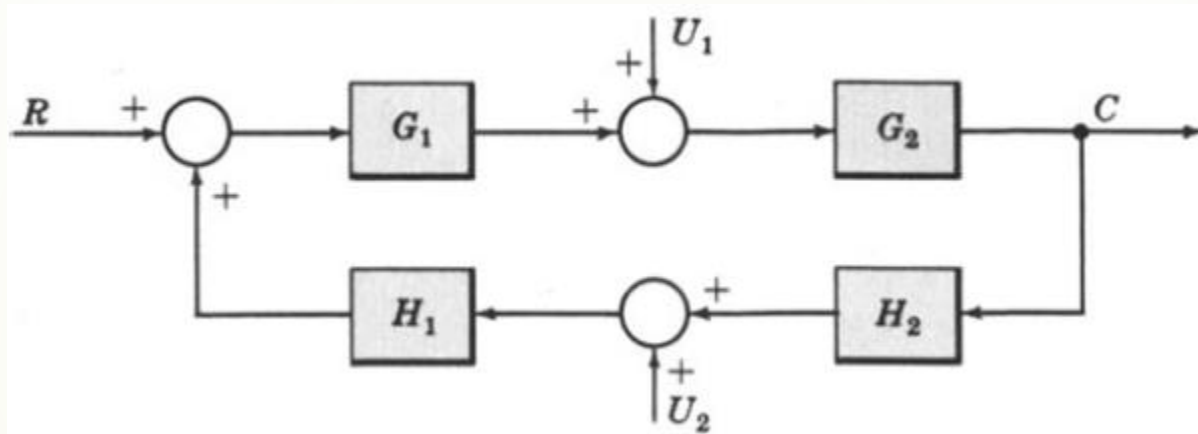
Example-15: Continue

Step 5: The total output is $C = C_R + C_U$

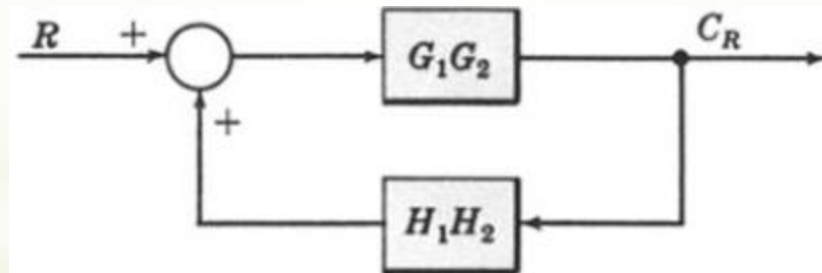
$$= \left[\frac{G_1 G_2}{1 + G_1 G_2} \right] R + \left[\frac{G_2}{1 + G_1 G_2} \right] U$$

$$= \left[\frac{G_2}{1 + G_1 G_2} \right] [G_1 R + U]$$

Example-16: **Multiple-Input System**. Determine the output C due to inputs R , U_1 and U_2 using the Superposition Method.



Let $U_1 = U_2 = 0$.



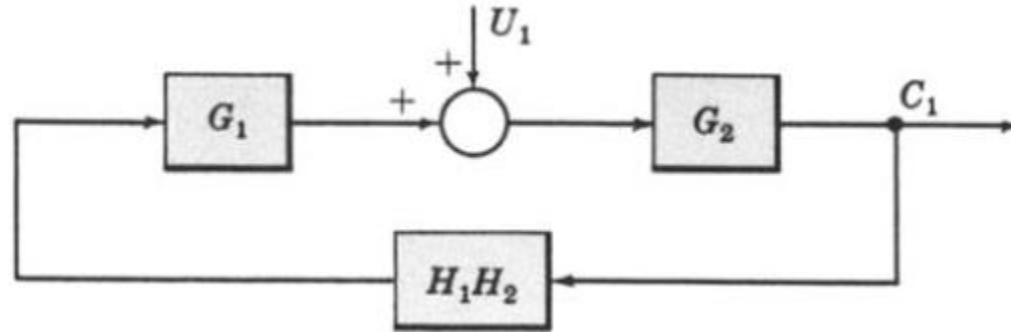
$$C_R = [G_1G_2 / (1 - G_1G_2H_1H_2)] R$$

where C_R is the output due to R acting alone.

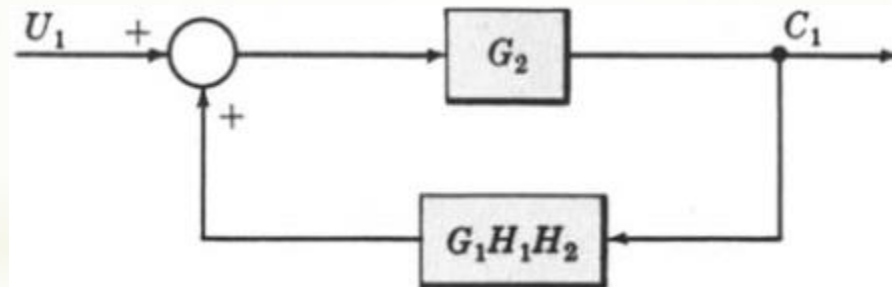
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Example-16: Continue

Now let $R = U_2 = 0$.



Rearranging the blocks, we get

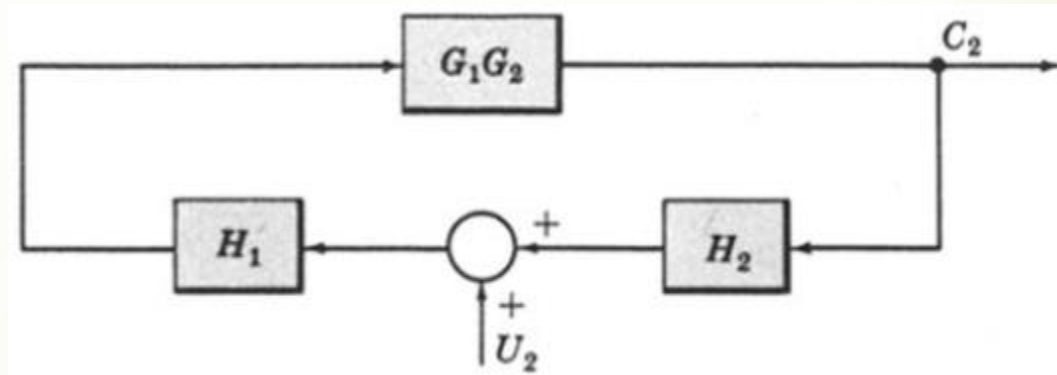


$$C_1 = [G_2 / (1 - G_1G_2H_1H_2)]U_1$$

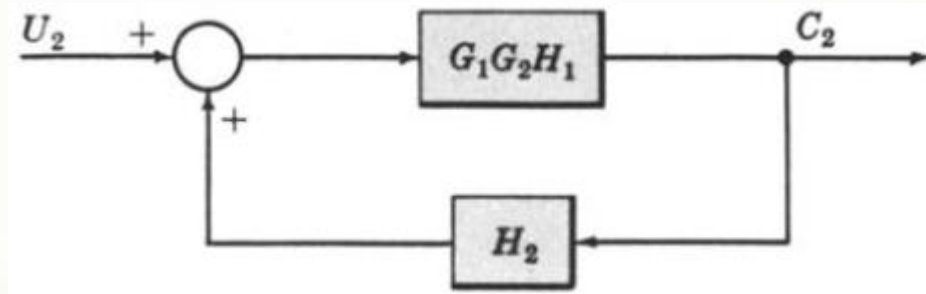
where C_1 is the response due to U_1 acting alone.

Example-16: Continue

Finally, let $R = U_1 = 0$.



Rearranging the blocks, we get



$$C_2 = [G_1 G_2 H_1 / (1 - G_1 G_2 H_1 H_2)] U_2$$

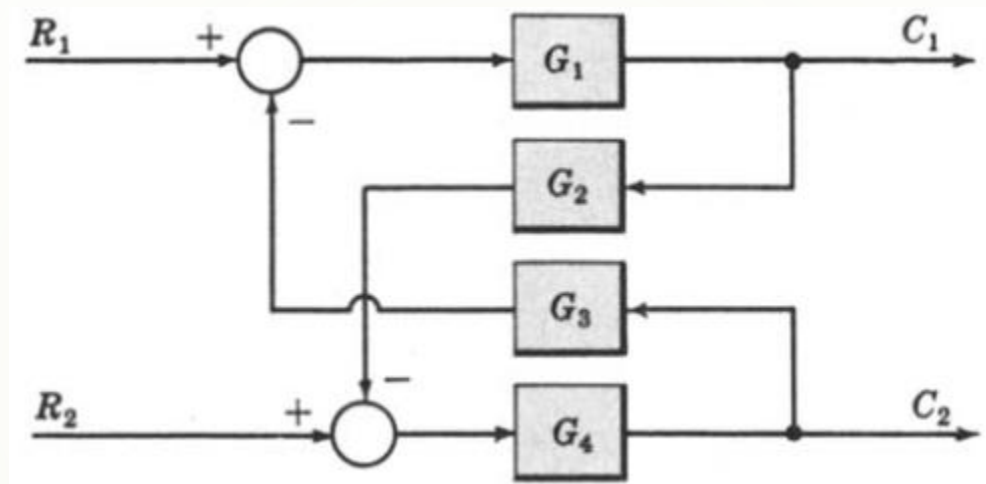
where C_2 is the response due to U_2 acting alone.

By superposition, the total output is

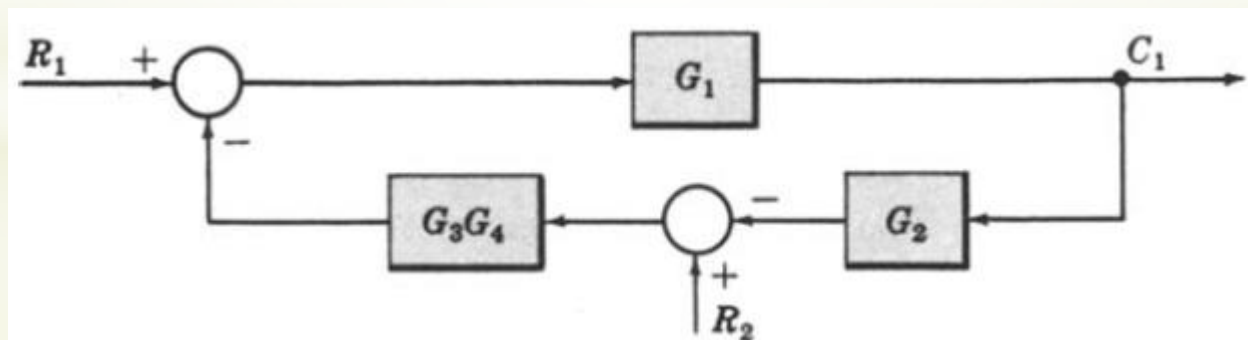
$$C = C_R + C_1 + C_2 = \frac{G_1 G_2 R + G_2 U_1 + G_1 G_2 H_1 U_2}{1 - G_1 G_2 H_1 H_2}$$

Example-17: Multi-Input Multi-Output System.

Determine C_1 and C_2 due to R_1 and R_2 .

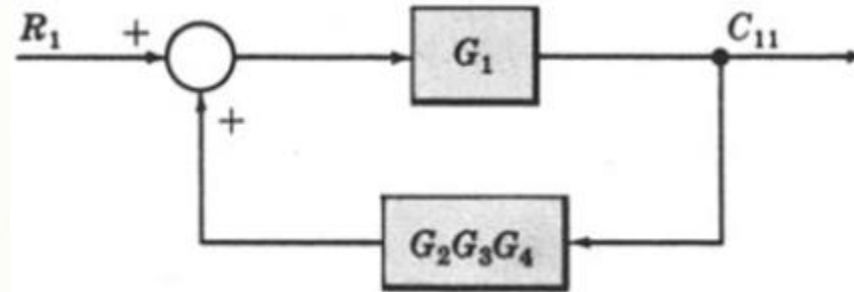


First ignoring the output C_2 .



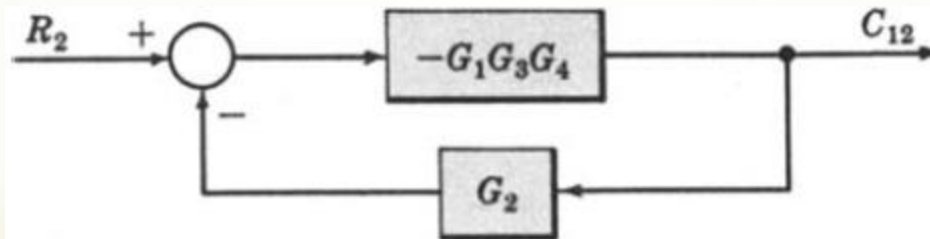
Example-17: Continue

Letting $R_2 = 0$ and combining the summing points,



Hence C_{11} , the output at C_1 due to R_1 alone, is $C_{11} = G_1 R_1 / (1 - G_1 G_2 G_3 G_4)$.

For $R_1 = 0$,

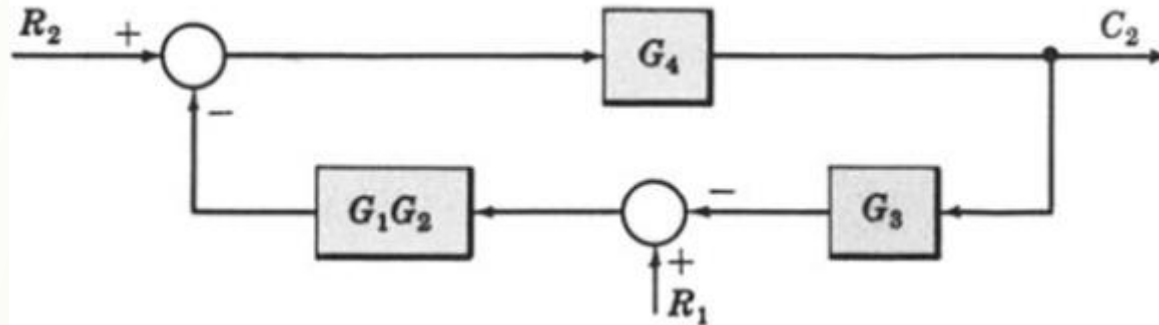


Hence $C_{12} = -G_1 G_3 G_4 R_2 / (1 - G_1 G_2 G_3 G_4)$ is the output at C_1 due to R_2 alone.

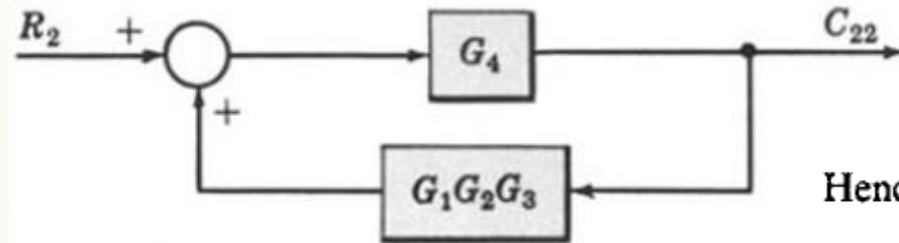
Thus $C_1 = C_{11} + C_{12} = (G_1 R_1 - G_1 G_3 G_4 R_2) / (1 - G_1 G_2 G_3 G_4)$

Example-17: Continue

Now we reduce the original block diagram, ignoring output C_1 .

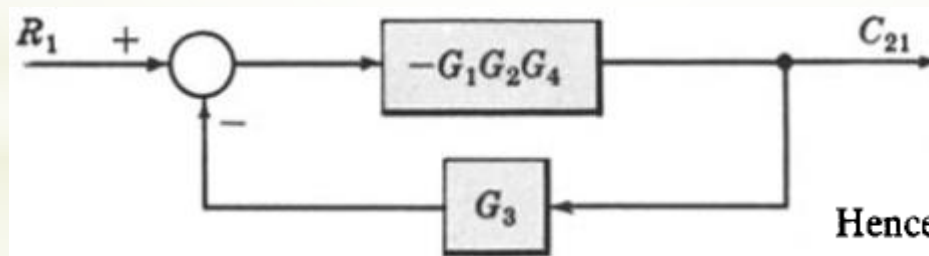


When $R_1 = 0$,



Hence $C_{22} = G_4 R_2 / (1 - G_1 G_2 G_3 G_4)$

When $R_2 = 0$,

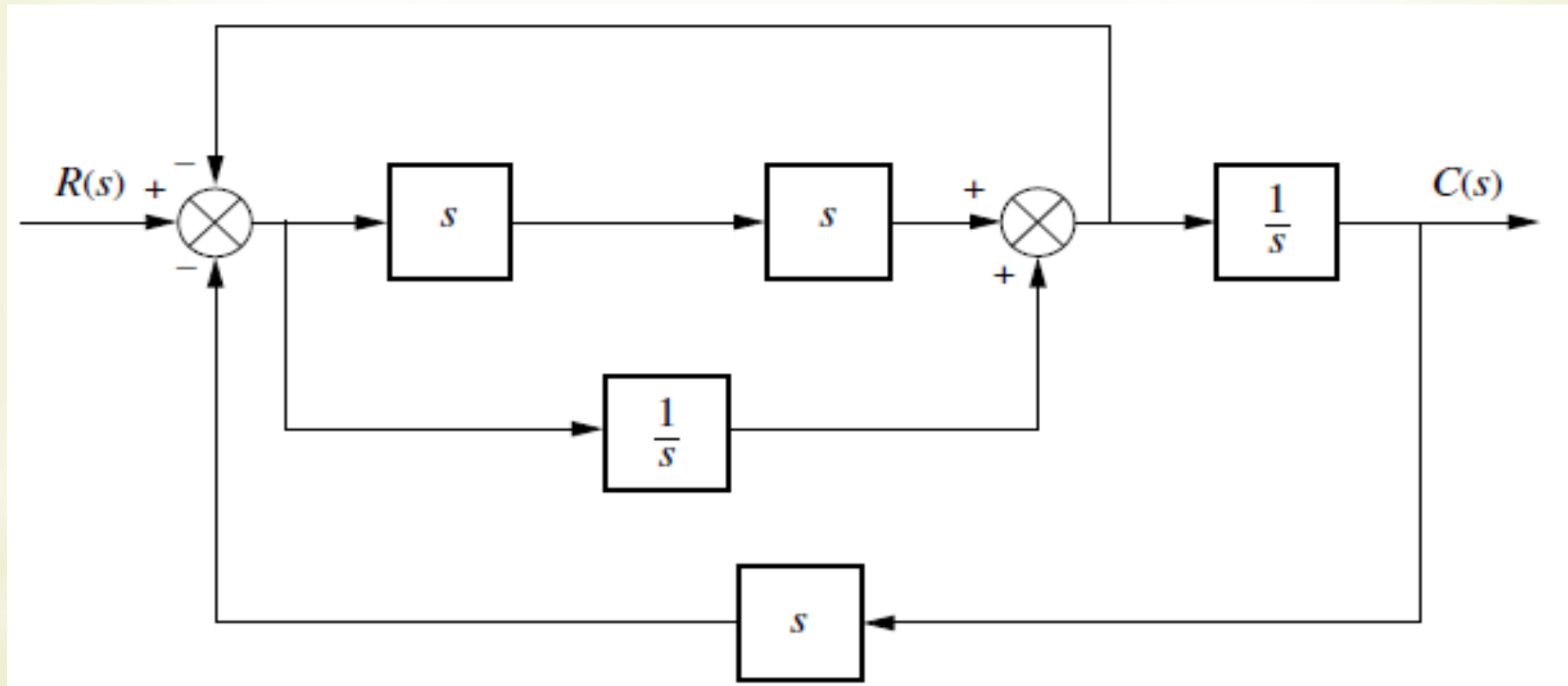


Hence $C_{21} = -G_1 G_2 G_4 R_1 / (1 - G_1 G_2 G_3 G_4)$

Finally, $C_2 = C_{22} + C_{21} = (G_4 R_2 - G_1 G_2 G_4 R_1) / (1 - G_1 G_2 G_3 G_4)$

Skill Assessment Exercise:

PROBLEM: Find the equivalent transfer function, $T(s) = C(s)/R(s)$, for the system

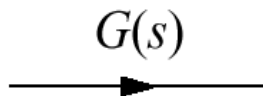


Answer of Skill Assessment Exercise:

ANSWER: $T(s) = \frac{s^3 + 1}{2s^4 + s^2 + 2s}$

Signal-flow Graph Components

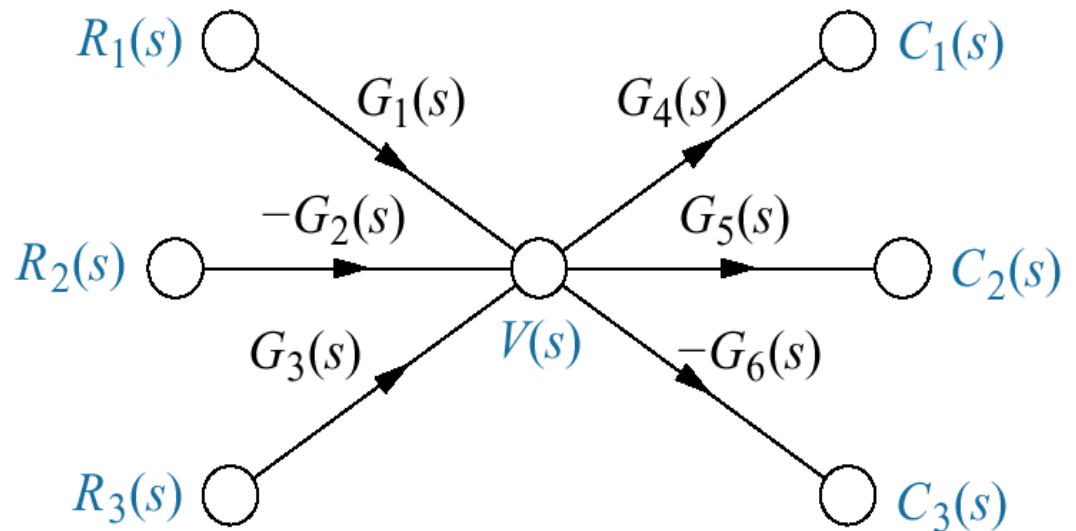
- a. system;
- b. signal;
- c. interconnection of systems and signals



(a)



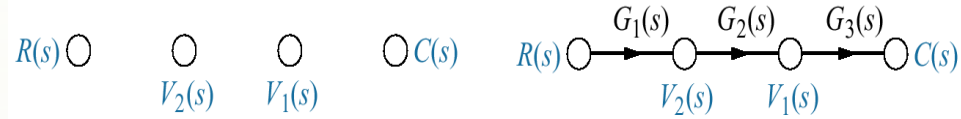
(b)



(c)

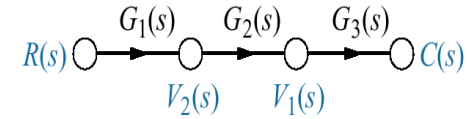
Building Signal-flow Graphs

a. Cascaded system nodes



(a)

b. Cascaded system signal-flow graph;



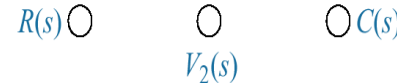
(b)

c. Parallel system nodes



(c)

d. Parallel system signal-flow graph;



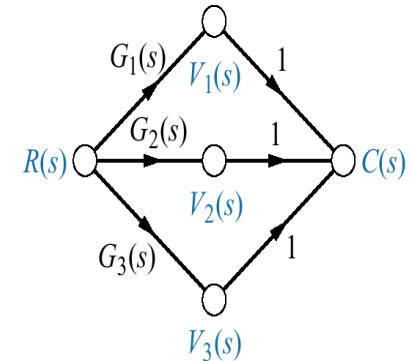
(d)

e. Feedback system nodes

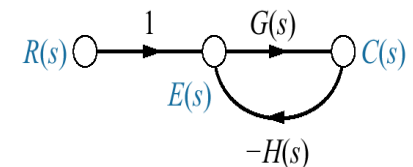
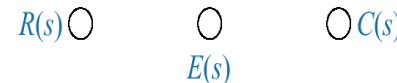


(e)

f. Feedback system signal-flow graph



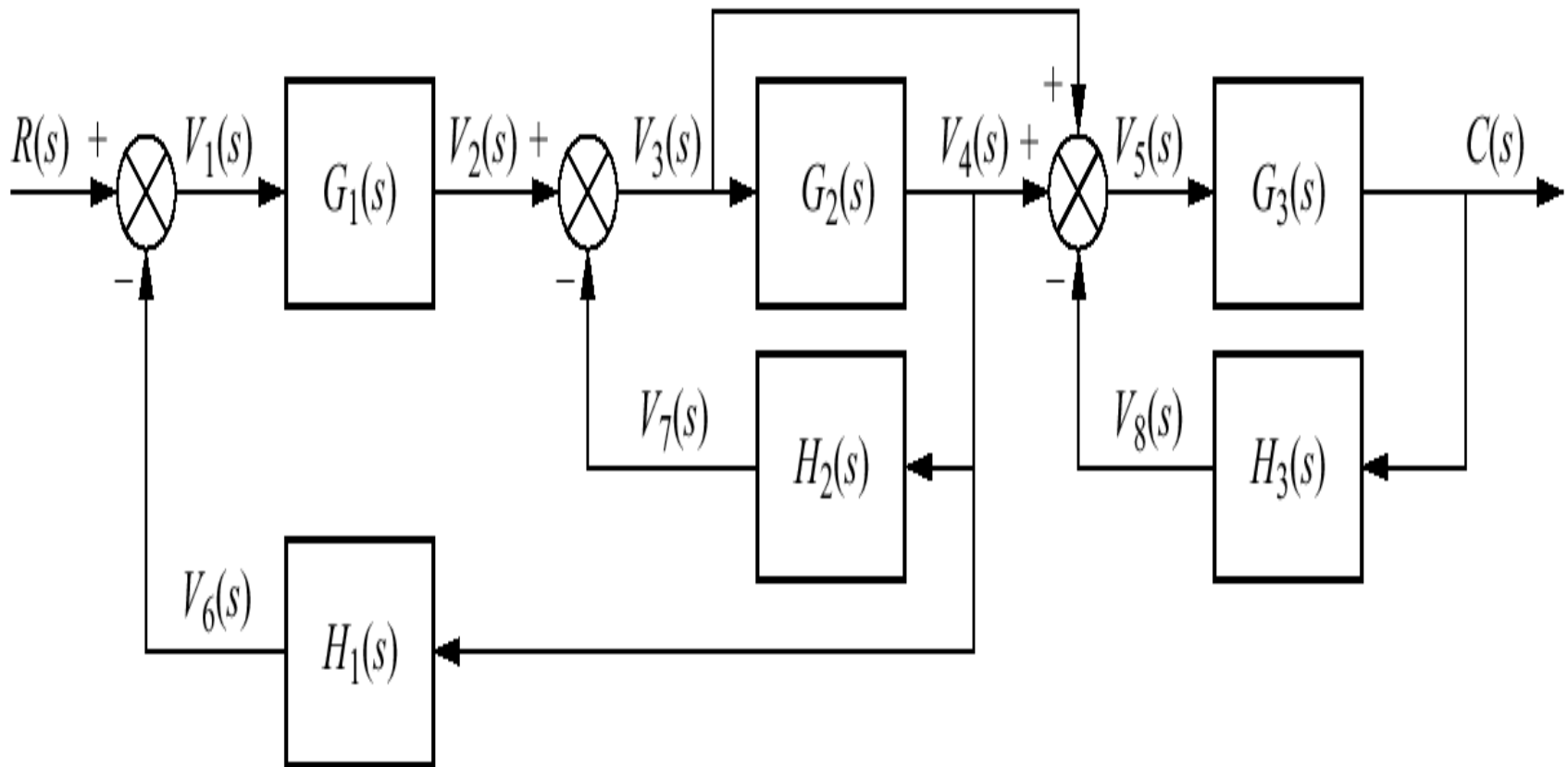
(f)



(f)

Converting a Block Diagram to a Signal-flow Graph

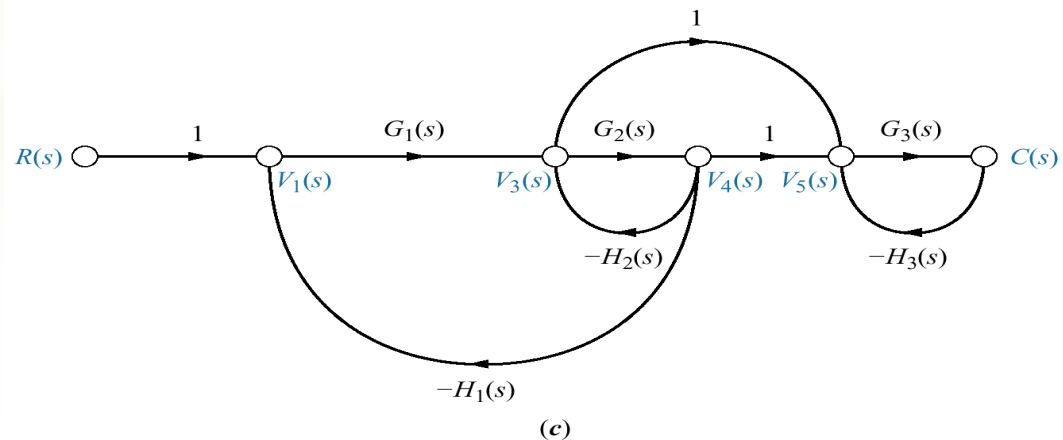
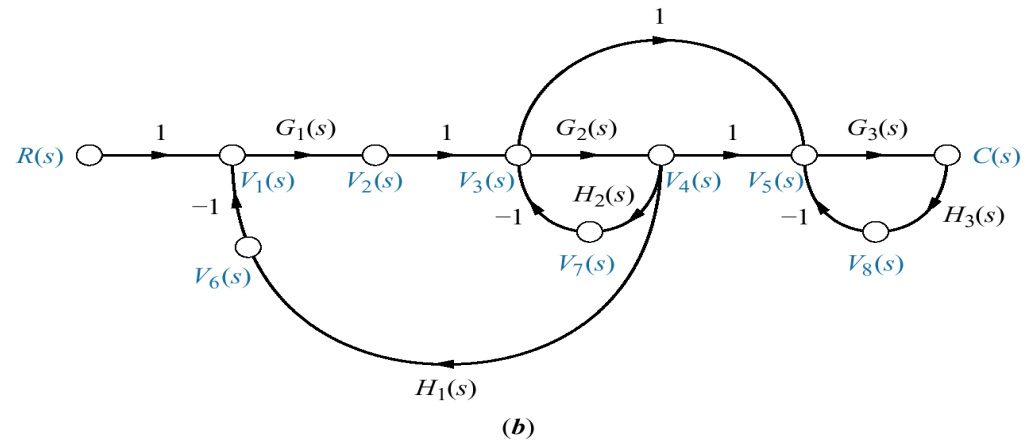
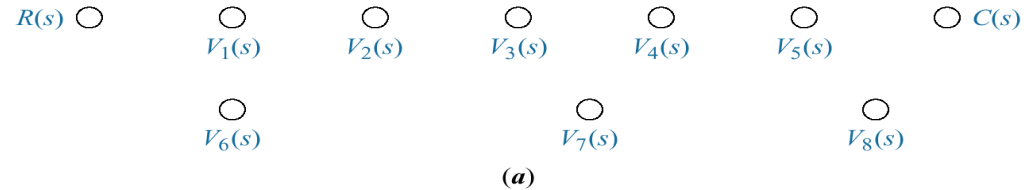
Problem: Convert the block diagram to a signal-flow graph.



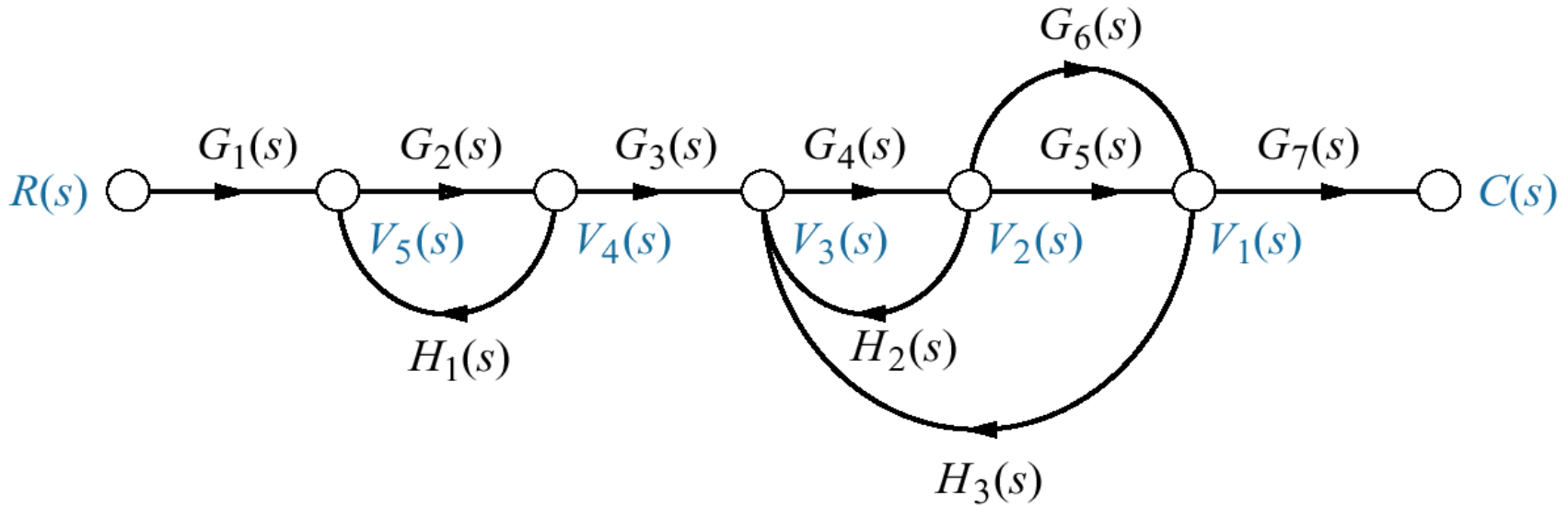
Converting a Block Diagram to a Signal-flow Graph

Signal-flow graph development:

- a. signal nodes;
- b. signal-flow graph;
- c. simplified signal-flow graph



Mason's Rule - Definitions



Loop gain “ L_k ”: The product of branch gains found by traversing a path that starts at a node and ends at the same node, following the direction of the signal flow, without passing through any other node more than once.

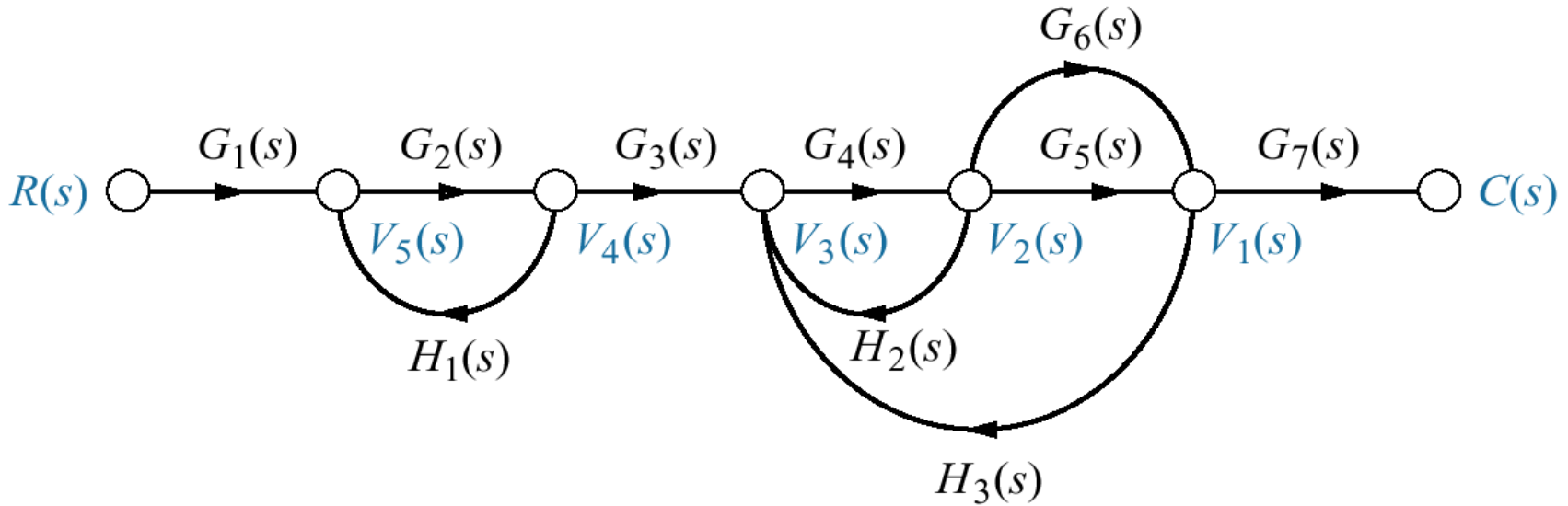
$$G_2(s)H_1(s), \quad G_4(s)H_2(s), \quad G_4(s)G_5(s)H_3(s),$$

$$G_4(s)G_6(s)H_3(s)$$

Forward-path gain “ P_k ”: The product of gains found by traversing a path from input node to output node in the direction of signal flow.

$$G_1(s)G_2(s)G_3(s)G_4(s)G_5(s)G_7(s), \quad G_1(s)G_2(s)G_3(s)G_4(s)G_6(s)G_7(s)$$

Mason's Rule - Definitions



Nontouching loops: loops that do not have any nodes in common. $G_2(s)H_1(s)$ does not touch $G_4(s)H_2(s)$, $G_4(s)G_5(s)H_3(s)$, and $G_4(s)G_6(s)H_3(s)$

Nontouching-loop gain: The product of loop gains from nontouching loops taken 2, 3, 4, or more at a time.

$$[G_2(s)H_1(s)][G_4(s)H_2(s)], \quad [G_2(s)H_1(s)][G_4(s)G_5(s)H_3(s)], \\ [G_2(s)H_1(s)][G_4(s)G_6(s)H_3(s)]$$

Mason's Rule

The Transfer function. $C(s)/R(s)$, of a system represented by a signal-flow graph is

$$G(s) = \frac{C(s)}{R(s)} = \frac{\sum_k P_k \Delta_k}{\Delta}$$

Where

K = number of forward paths

P_k = the k^{th} forward-path gain

Δ = $1 - \sum$ loop gains + \sum nontouching-loop gains taken 2 at a time - \sum nontouching-loop gains taken 3 at a time + \sum nontouching-loop gains taken 4 at a time -

Δ_k = $1 -$ loop gain terms that does not touch the k^{th} forward path.

Transfer Function via Mason's Rule

Problem: Find the transfer function for the signal flow graph

Solution:

forward path

$$G_1(s)G_2(s)G_3(s)G_4(s)G_5(s)$$

Loop gains

$$G_2(s)H_1(s), G_4(s)H_2(s), G_7(s)H_4(s),$$

$$G_2(s)G_3(s)G_4(s)G_5(s)G_7(s)G_8(s)$$

Nontouching loops

2 at a time

$$G_2(s)H_1(s)G_4(s)H_2(s)$$

$$G_2(s)H_1(s)G_7(s)H_4(s)$$

$$G_4(s)H_2(s)G_7(s)H_4(s)$$

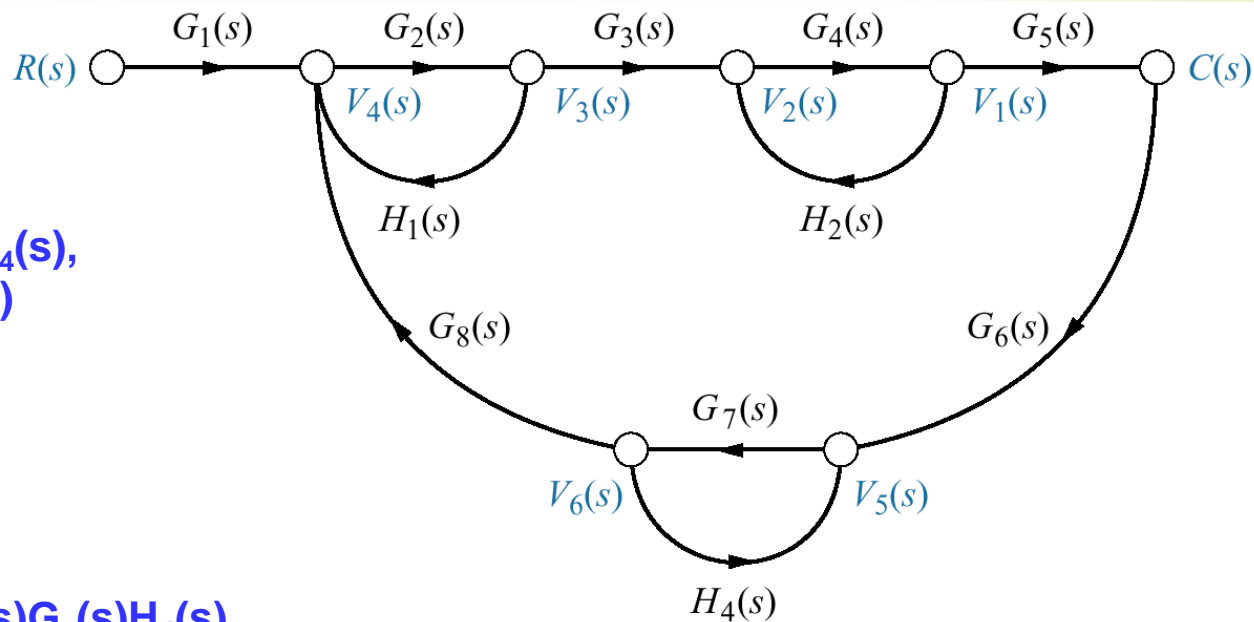
$$3 \text{ at a time } G_2(s)H_1(s)G_4(s)H_2(s)G_7(s)H_4(s)$$

Now

$$\Delta = 1 - [G_2(s)H_1(s) + G_4(s)H_2(s) + G_7(s)H_4(s) + G_2(s)G_3(s)G_4(s)G_5(s)G_7(s)G_8(s)] + [G_2(s)H_1(s)G_4(s)H_2(s) + G_2(s)H_1(s)G_7(s)H_4(s) + G_4(s)H_2(s)G_7(s)H_4(s)] - [G_2(s)H_1(s)G_4(s)H_2(s)G_7(s)H_4(s)]$$

$$\Delta_1 = 1 - G_7(s)H_4(s)$$

$$G(s) = \frac{P_1 \Delta_1}{\Delta} = \frac{[G_1(s)G_2(s)G_3(s)G_4(s)G_5(s)][1 - G_7(s)H_4(s)]}{\Delta}$$

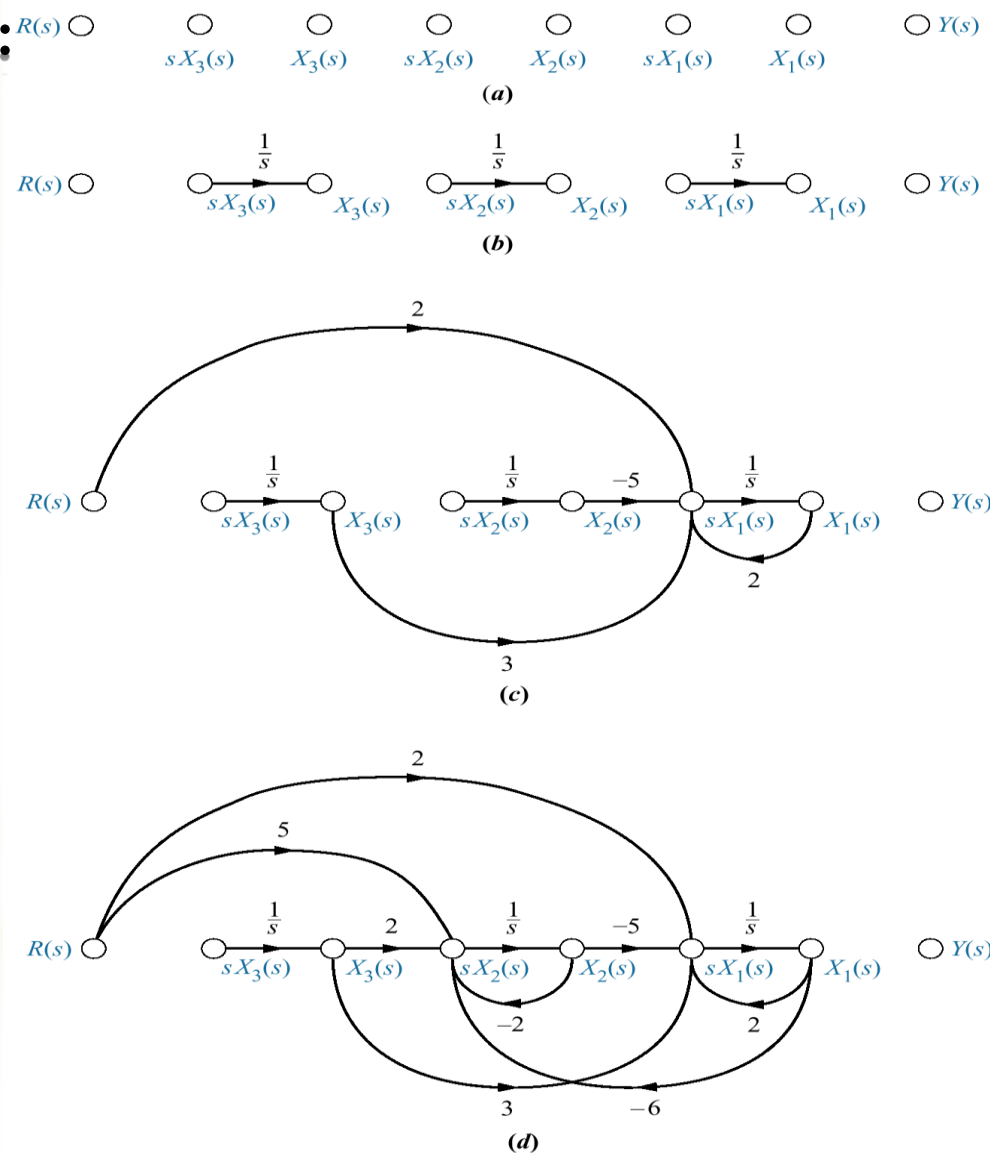


Signal-Flow Graphs of State Equations

Problem: draw signal-flow graph for:

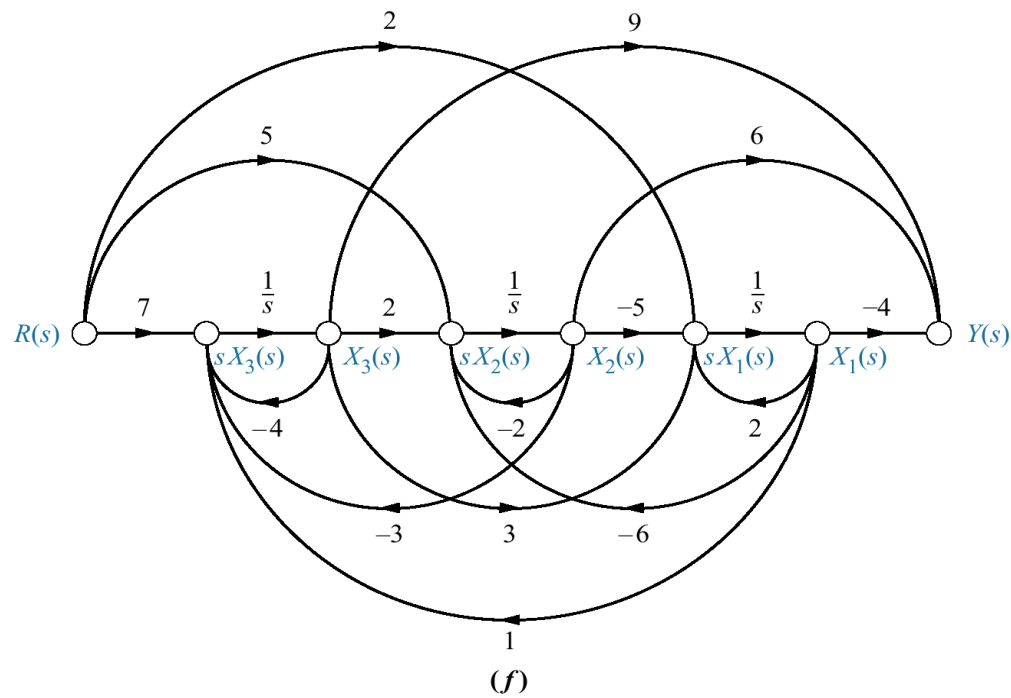
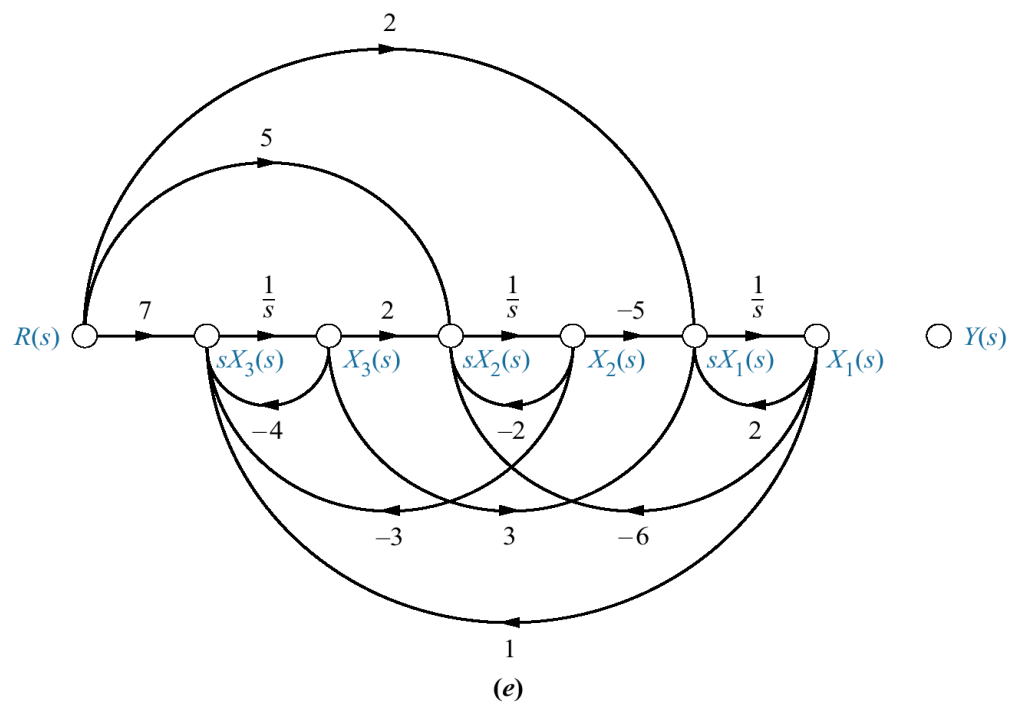
- $x_1 = 2x_1 - 5x_2 + 3x_3 + 2r$
- $x_2 = -6x_1 - 2x_2 + 2x_3 + 5r$
- $x_3 = x_1 - 3x_2 - 4x_3 + 7r$
- $y = -4x_1 + 6x_2 + 9x_3$

- a. place nodes;
- b. interconnect state variables and derivatives;
- c. form dx_1/dt ;
- d. form dx_2/dt



Signal-Flow Graphs of State Equations

(continued)
 e. form dx_3/dt ;
 f. form output



\mathcal{A}

With Our Best Wishes
Automatic Control (1)
Course Staff

Associate Prof. Dr. Mohamed Ahmed Ebrahim

Thank You
For Your Attention



*Mohamed Ahmed
Ebrahim*

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